



# On Detection of Median Filtering in Digital Images

Electronic Imaging 2010  
Media Forensics and Security II

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# Outline of this Talk

1 Motivation: Detection of Median Filtering?

2 Detection in never-compressed images

3 Detection in JPEG compressed images

4 Conclusion

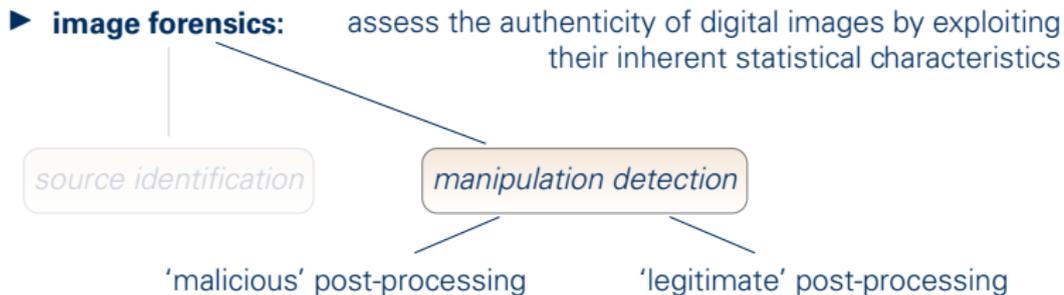
# Digital Image Forensics

- ▶ **image forensics:** assess the authenticity of digital images by exploiting their inherent statistical characteristics

*source identification*

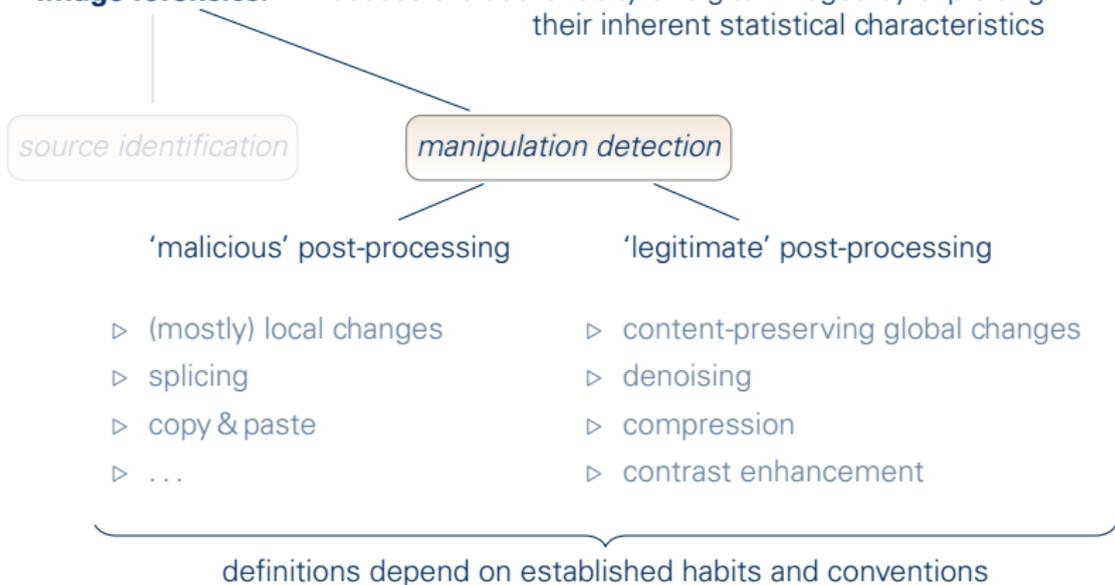
*manipulation detection*

# Digital Image Forensics



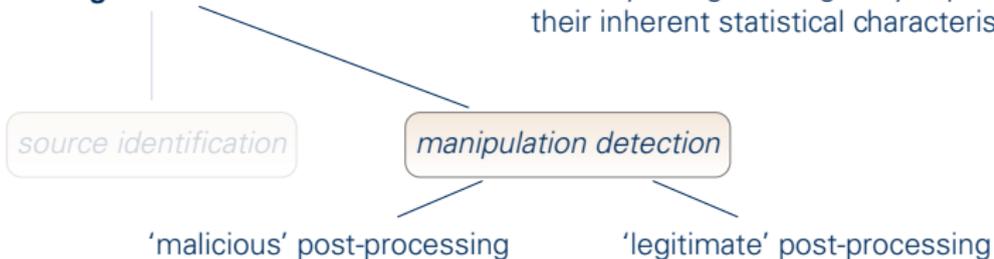
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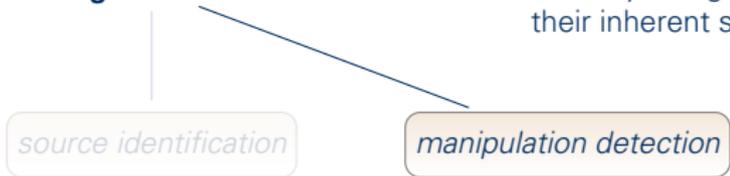
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'malicious' post-processing

'legitimate' post-processing



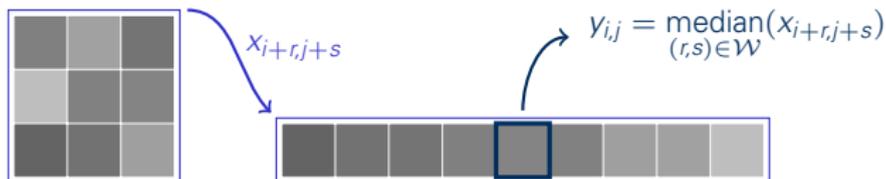
pictures: Andrea Sommer, Doc Baumann

# Processing History of Digital Images

- ▶ 'malicious' post-processing is generally considered to be more critical
- but:** general processing history of digital images is of great interest
- ▶ state of the image prior to the actual ('malicious') manipulation may influence
    - ▷ the choice of suitable forensic tools
    - ▷ the interpretation of results obtained with these tools(this applies also to steganalysis) [Böhme, 2009]
  - ▶ 'legitimate' post-processing can interfere with or even wipe out subtle traces of previous manipulations
    - ▷ decreased reliability of forensic methods

# Detection of Median Filtering

- ▶ median filter is a well-known **non-linear** denoising and smoothing operator



## Why is the detection of median filtering of interest?

- ▶ forensic methods often rely on some kind of linearity assumption
  - ▷ vulnerable to median filtering [Kirchner & Böhme, 2008]
- ▶ smooth(ed) images may require a specific treatment in various applications

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## Median filtering is hard to model analytically

- ▶ highly non-linear and signal-adaptive
- ▶ most image processing literature assumes i.i.d. samples

# Streaking

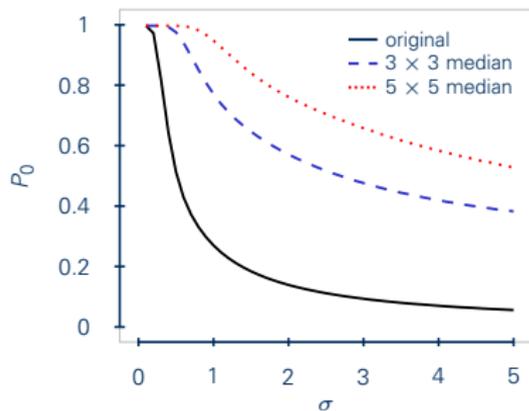
- ▶ output pixel is drawn directly from the set of input samples
- ▶ non-zero probability that output pixels in a certain neighborhood originate from the same input pixel → **streaking** [Bovik, 1987]
- ▶ median filtering increases  $P_0 = \Pr(y_{i,j} = y_{k,l})$

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- ▶ median filtering increases  $P_0 = \Pr(y_{i,j} = y_{k,l})$  indication of median filtering
- ▶ for continuous-valued i.i.d. input samples,  $P_0$  is distribution-independent

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- ▶ for continuous-valued i.i.d. input samples,  $P_0$  is distribution-independent, but not for discrete signals



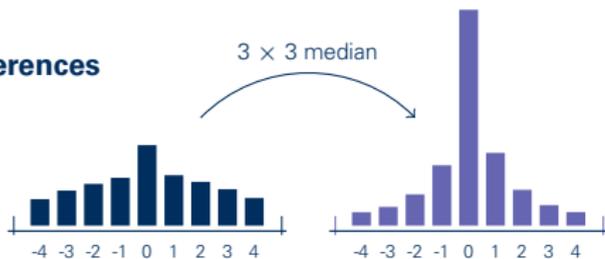
streaking probabilities for direct vertical/horizontal neighbors and quantized i.i.d. Gaussian  $\mathcal{N}(0, \sigma)$  input samples

# Measuring Streaking Artifacts in Real Images

- ▶ histogram of the **first-order differences**

$$d_{i,j} = y_{i,j} - y_{i+k,j+l} \text{ with lag } (k, l)$$

- ▶ increased peak  $h_0$   
due to median filtering

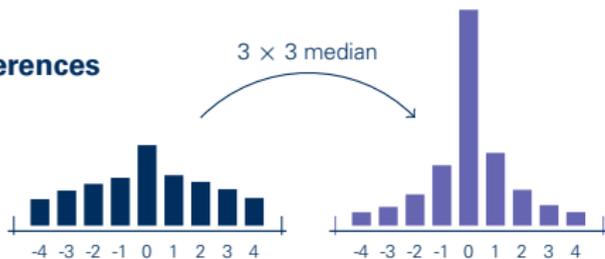


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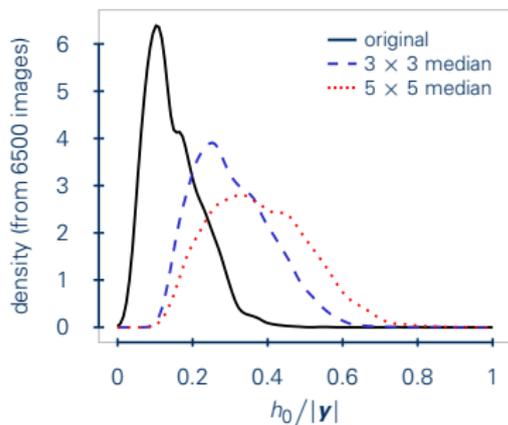
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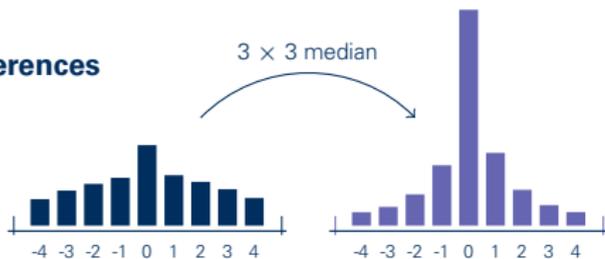


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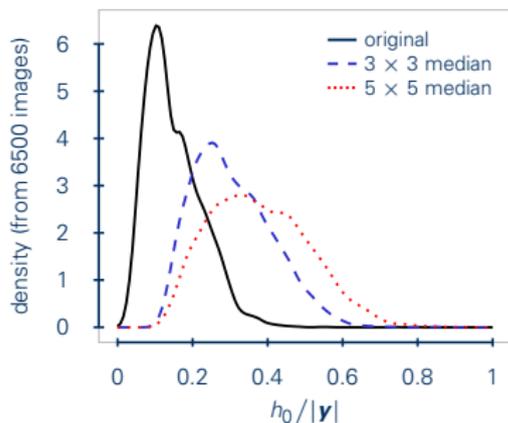
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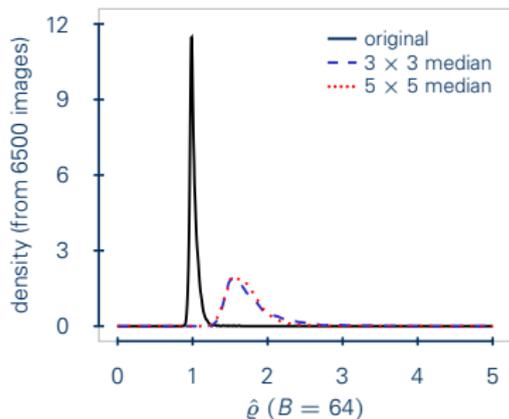


- ▶ median filtering increases  $h_0$  relative to  $h_1$
- ▶ **normalized measure:**  $\varrho = h_0/h_1$
- ▶  $\varrho \gg 1$  for median filtered images

# Robust Measure

- ▶ saturation effects are likely to cause false positives
- ▶ assumption: saturation is mostly a localized phenomenon
- ▶ measure streaking artifacts in the set  $\mathcal{B}$  of all non-overlapping  $B \times B$  blocks

$$\hat{\rho} = \operatorname{median}_{b \in \mathcal{B}}(w_b \rho_b) \quad \text{with weights} \quad w_b = 1 - \left( \frac{h_0}{B^2 - B} \right)$$

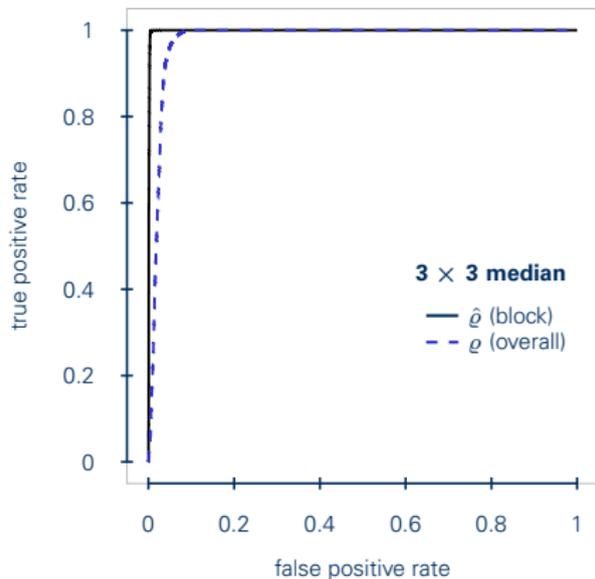


- ▶ generally good discrimination between original and filtered images

# Experimental Results

## overall vs. block-based measure

- ▷ database of 6500 images from 22 different cameras
- ▷ never-compressed images, converted to grayscale
- ▷  $(k, l) = (1, 0)$

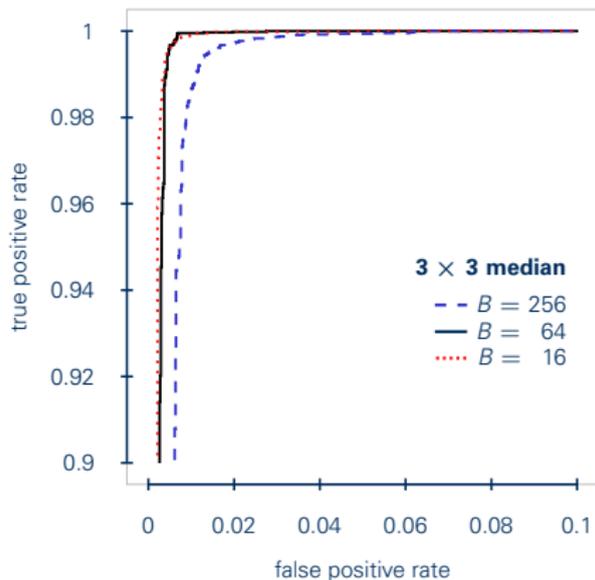


- ▶ block-based approach ( $B = 64$ ) is more robust to outliers
- ▶ perfect detection for FPR  $< 1.8\%$

# Experimental Results

## influence of block size

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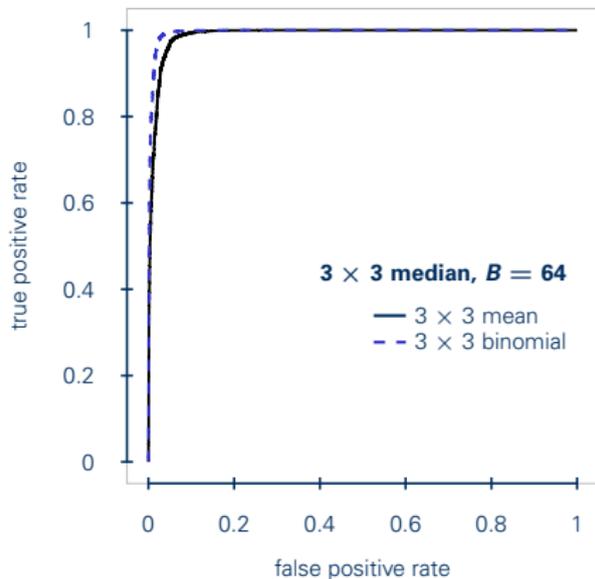


- ▶ ROC curves for block-based approach
- ▶  $\hat{q}$  superior for smaller blocks
- ▶ too small blocks do not yield additional gain (overall amount of saturation remains the same)
- ▶  $B = 64$  suitable choice (for this set of images)

# Experimental Results

## alternative smoothers

- ▷ database of 6500 images from 22 different cameras
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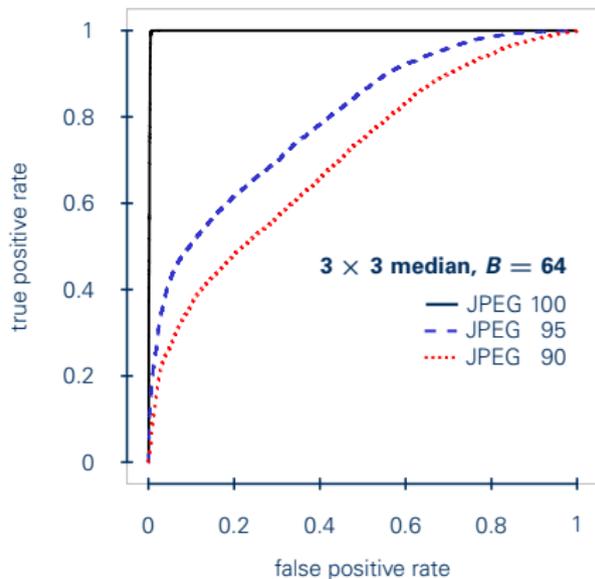


- ▶ ROC curves obtained by taking linearly smoothed images as 'originals'
- ▶ detector can well distinguish between median filtered and otherwise smoothed images

# Experimental Results

## JPEG post-compression

- ▷ database of 6500 images from 22 different cameras
- ▷ never-compressed images, converted to grayscale
- ▷  $(k, l) = (1, 0)$

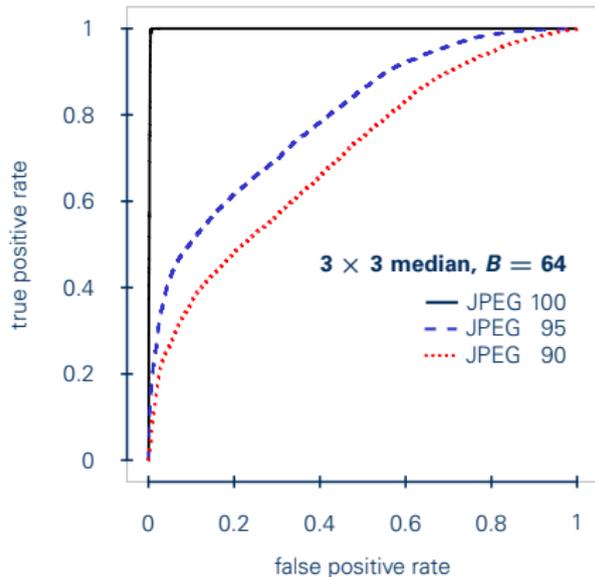


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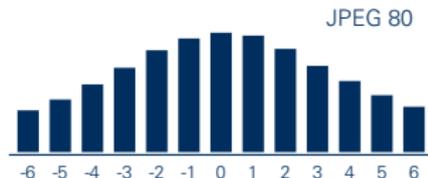


- ▶ detector is not robust against JPEG compression
- ▶ JPEG smooths the first order differences histogram
- ▶ JPEG introduces false alarms

# SPAM Features for Median Detection

- ▶ smoothing generally affects first-order differences
  - ▷ peaky distribution
  - ▷ further 'enhanced' by subsequent JPEG compression
- ▶ strongest effects for small differences  $|d_{i,j}| \leq T$

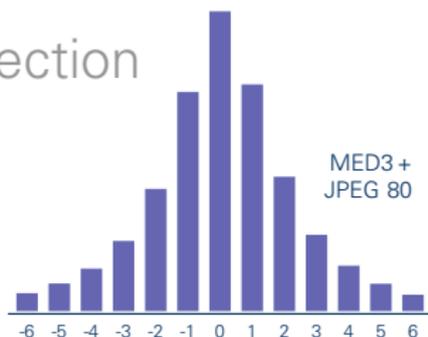
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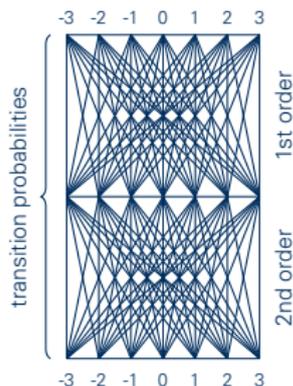
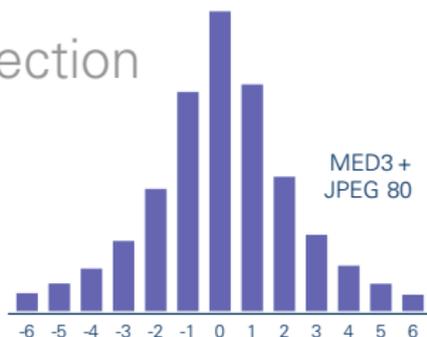


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- ▶ more sophisticated model: **SPAM features**  
[Pevný et al., MM-Sec 2009]
- ▶ subtractive pixel adjacency matrix models first-order differences as  $n$ -th order Markov chain
- ▶ transition probabilities (= conditional joint distribution) taken as features in a high-dimensional classification problem



# SPAM Details

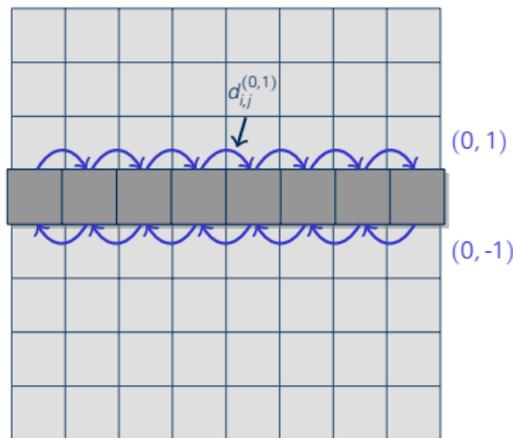
- ▶ transition probabilities for first-order differences  $d_{ij}^{(k,l)}$  with lag  $(k, l) \in \{-1, 0, 1\}^2$

$$M_{\delta_n, \dots, \delta_0}^{(k,l)} = P\left(d_{i+kn, j+ln}^{(k,l)} = \delta_n \mid d_{i+k(n-1), j+l(n-1)}^{(k,l)} = \delta_{n-1}, \dots, d_{ij}^{(k,l)} = \delta_0\right)$$

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- ▶ horizontal/vertical transition matrices

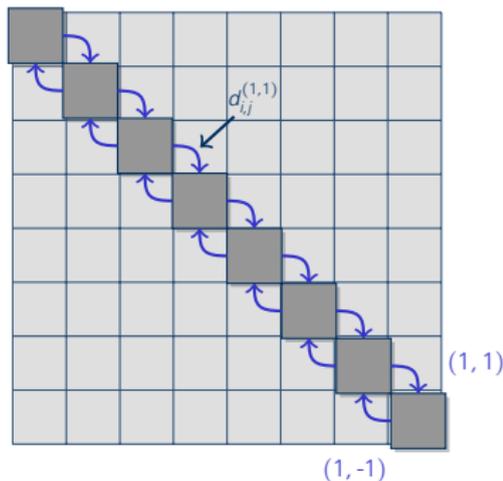
$$\mathbf{M}^{(0,1)} \quad \mathbf{M}^{(0,-1)}$$

$$\mathbf{M}^{(1,0)} \quad \mathbf{M}^{(-1,0)}$$

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- ▶ diagonal transition matrices

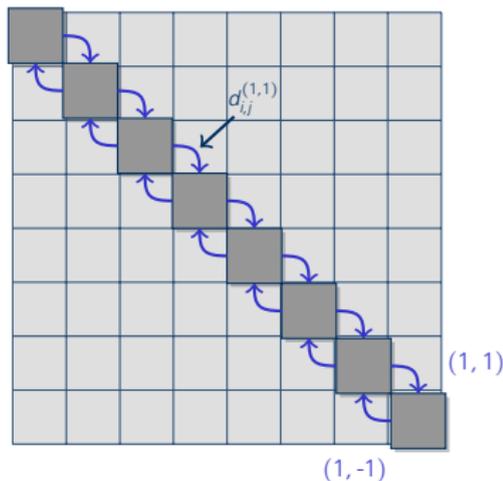
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- ▶ horizontal/vertical features

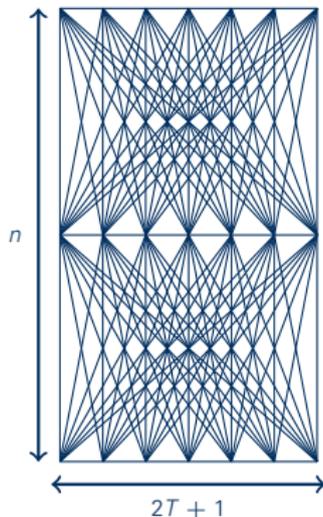
$$\mathbf{F}^{(h/v)} = 1/4 \left( \mathbf{M}^{(0,1)} + \mathbf{M}^{(0,-1)} + \mathbf{M}^{(1,0)} + \mathbf{M}^{(-1,0)} \right)$$

- ▶ diagonal features

$$\mathbf{F}^{(d)} = 1/4 \left( \mathbf{M}^{(1,1)} + \mathbf{M}^{(1,-1)} + \mathbf{M}^{(-1,-1)} + \mathbf{M}^{(-1,1)} \right)$$

# SPAM Classifier

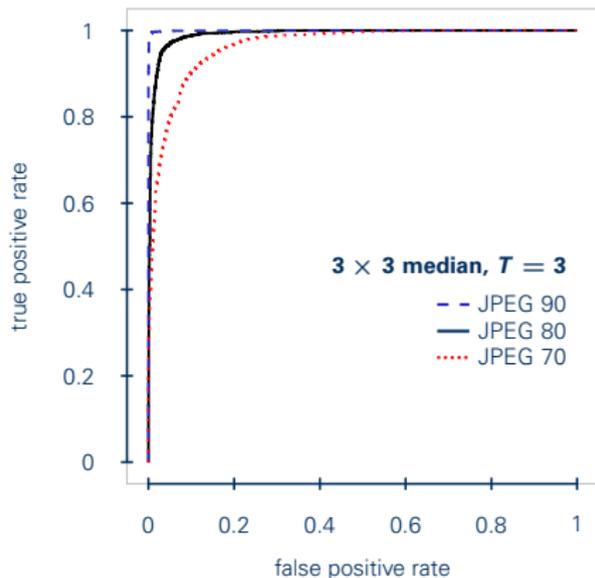
- ▶ **number of features:**  $2(2T + 1)^{n+1}$
- ▶ in our tests:  $n = 2$  and  $T \in \{1, 2, 3\}$ 
  - ▷ up to 686 features
- ▶ soft-margin SVM with Gaussian kernel
  - ▷ one classifier per filter size and JPEG post-compression quality
  - ▷ parameter search and training with  $\approx 3250$  images per class (five-fold cross-validation)
  - ▷ validation with another  $\approx 3250$  images per class



# Experimental Results

## SPAM features

- ▷ database of 6500 images from 22 different cameras
- ▷ never-compressed images, converted to grayscale
- ▷  $512 \times 512$  center region

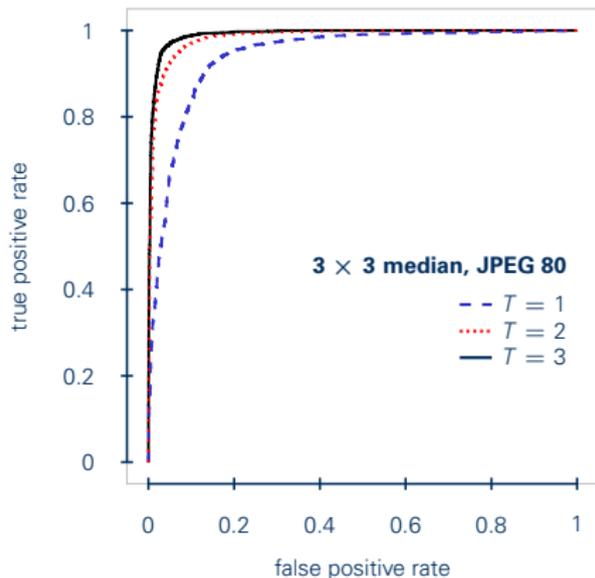


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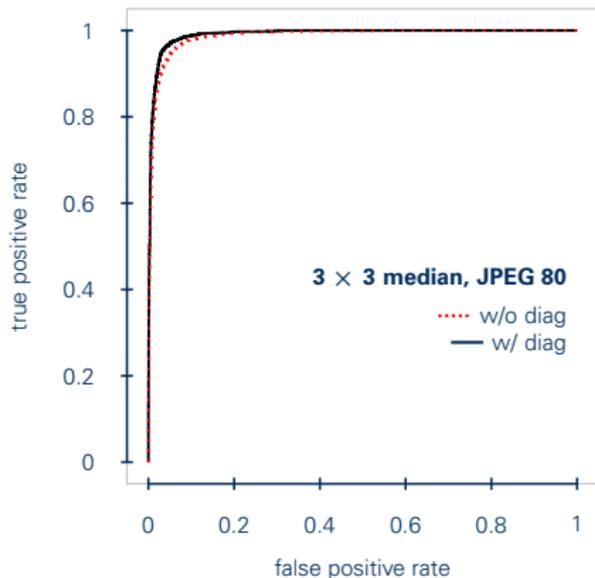


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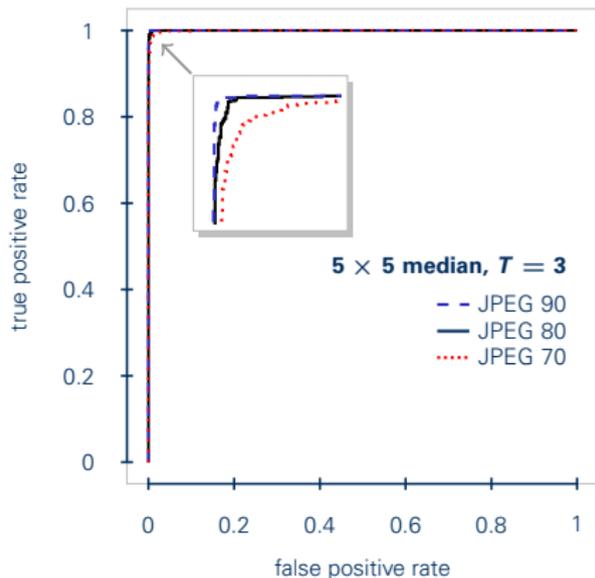


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- ▶ higher SPAM dimensionality increases performance
- ▶ diagonal features do not provide additional information beyond horizontal/vertical features
- ▶ considerably improved performance for larger filter sizes

# Further Experiments

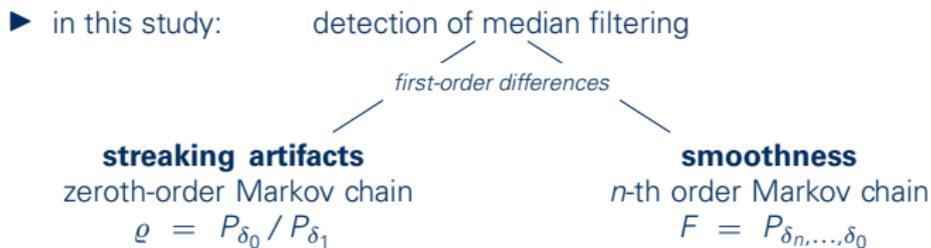
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# Further Experiments

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- ▶ larger images result in better performance
- ▶ pre-median JPEG compression does not seem to influence detection results
  
- ▶ SPAM features **cannot** distinguish between median filter and other smoothers
  - ▷ similar effects w. r. t. the distribution of small first-order differences
  - ▷ **SPAM as a general-purpose smoothing detector?**

# Concluding Remarks

- ▶ general processing history is of great interest in various situations
  - ▷ make **informed decisions** in image forensics, steganalysis and watermarking



- ▶ JPEG post-compression obfuscates the actual type of smoothing
  - ▷ SPAM as general-purpose detector
  - ▷ explore alternative / additional features that are more specific to median filtering



# Thanks for your attention

## Questions?

Matthias Kirchner<sup>†</sup>, Jessica Fridrich<sup>‡</sup>

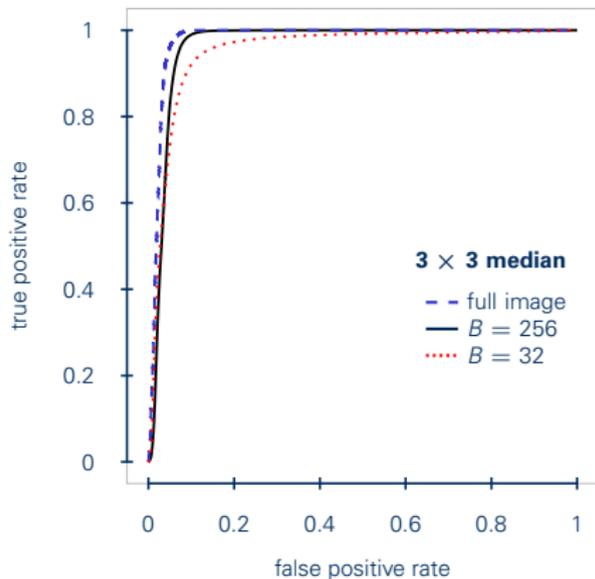
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Matthias Kirchner gratefully receives a doctorate scholarship from Deutsche Telekom Stiftung, Bonn, Germany.

# Experimental Results

## per-block decision

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- ▷ never-compressed images, converted to grayscale
- ▷  $(k, l) = (1, 0)$



- ▶ ROC curves over all non-overlapping blocks of all images
- ▶  $\varrho_b$  itself is more sensitive to local variations throughout the image
- ▶ larger blocks are beneficial for a per-block decision (local detection of median filtering)